

University of Mohamed Boudiaf M'sila
Faculty of Mathematics and Computer Science
Department of Computer Science
Master 01 SIGL

Duration: 1h30 (90 Minutes)

Instructor

DR. Hichem Debbi

Formal Verification and Specification
Final Exam
May 23, 2023

True/False

(03 points) Write True if the statement is true, otherwise write False.

- _____ $F\psi \equiv \psi \vee XF\psi$
- _____ nuSMV is a symbolic model checker
- _____ Equivalence checking is based on the abstraction/refinement principle.
- _____ It is not possible to implement an abstract machine without passing by the refinement step
- _____ pWq is true, if only if q is true
- _____ In B method, properties are predicates on constants

Section 2. Short Answer(02 points)

1. What is the difference between a liveness property and a safety property. Give an example for each one ?
2. Cite four (04) formal specification languages ?

Section 3. Method-B Specification(07 points)

3. Suppose that we have the following problem: The computer science department has a number of available *Datashows*:

```
_____ Abstract Machine
MACHINE data_show_reserve
SETS DataShows; /* abstract set of datashows */
reserved = ok, ko /* datashow used or not */
CONSTANTS max_Rsrc /* limit */
PROPERTIES max_Rsrc : 1..MAXINT
.....
```

1- Complete the abstract machine `data_show_reserve` by adding invariants, initialization, and the three following operations:

- **reserve**: for reserving a datashow.
- **free**: frees up a datashow
- **isReservedDatashow**: Checks whether a datashow is reserved or not.

2- Create an implementation for this abstract machine using arrays as total functions (Symbol: $-->$)

Section 4. ω -expressions(04 points)

4. Give the ω -regular expressions for the following Büchi automaton :

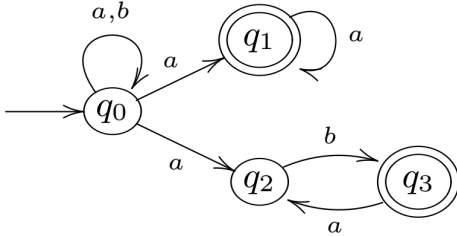


Figure 1: A

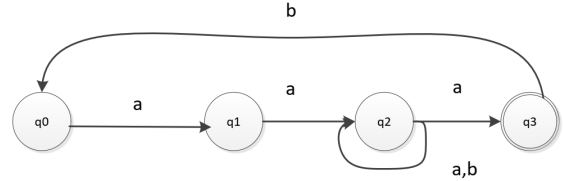


Figure 2: B

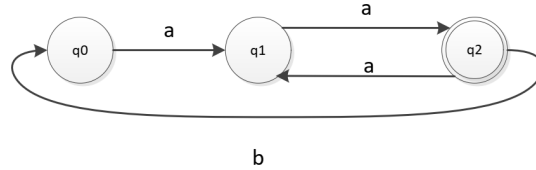


Figure 3: C

Section 5. CTL(04 points)

5. Consider the kripke structure presented in the figure below

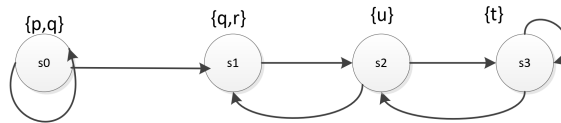


Figure 4: A Kripke structure

1- Construct its corresponding tree.

2 - Identify the set of states in which the following CTL properties are satisfied. Justify your response textually or by providing paths.

- EGq
- $EF(\neg r \wedge EXr)$
- $AGEGp$

Answer Key for Exam A

True/False

(03 points) Write True if the statement is true, otherwise write False.

True $F\psi \equiv \psi \vee XF\psi$

True nuSMV is a symbolic model checker

False Equivalence checking is based on the abstraction/refinement principle.

False It is not possible to implement an abstract machine without passing by the refinement step

False pWq is true, if only if q is true

True In B method, properties are predicates on constants

Section 2. Short Answer(02 points)

1. What is the difference between a liveness property and a safety property. Give an example for each one ?

Answer: See course.

2. Cite four (04) formal specification languages ?

Answer: See course.

Section 3. Method-B Specification(07 points)

3. Suppose that we have the following problem: The computer science department has a number of available *Datashows*:

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- 1- Complete the abstract machine `data_show_reserve` by adding invariants, initialization, and the three following operations:

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- 2- Create an implementation for this abstract machine using arrays as total functions (Symbol: `-- >`)

Answer:

Section 4. ω -expressions(04 points)

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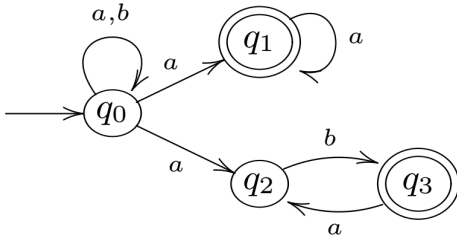


Figure 5: A

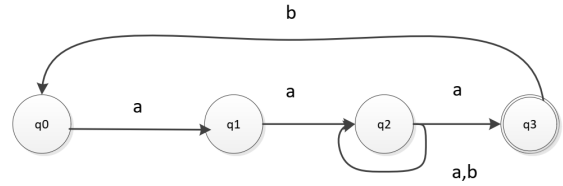


Figure 6: B

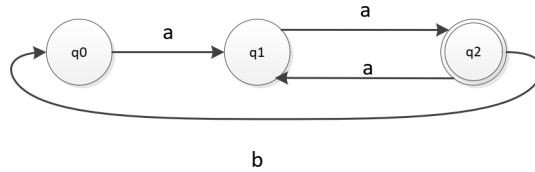


Figure 7: C

- Answer:**
- $(a + b)^* a^\omega + (a + b)^* a (ba)^\omega$
 - $(aa(a + b)^* ab)^\omega$
 - $((aa)^+ b)^\omega + ((aa)^+ b)^* a^\omega$

Section 5. CTL(04 points)

5. Consider the kripke structure presented in the figure below

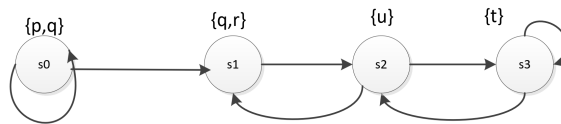


Figure 8: A Kripke structure

- 1- Construct its corresponding tree.
- 2 - Identify the set of states in which the following CTL properties are satisfied. Justify your response textually or by providing paths.

- EGq
- $EF(\neg r \wedge EXr)$
- $AGEGp$

- Answer:**
- only in s_0 . s_0 infinitely
 - is satisfied in all states. There is a path starting from s , such that in some state in the future $\neg r$ holds and such that in some next state r holds. The set of all states with $\neg r$ such that there exists a next state with r is $\{s_0, s_2\}$. Since we can reach s_0 (and s_1) from all states the formula holds for all states.

- There is no state (\emptyset). For every path starting in s , in each state on this path, $EG t$ must be true, i.e., it is possible to find a path starting there where p is always true. Example: in s_0 the property EGp holds, but not always since from s_1 on there is no path satisfying the property.