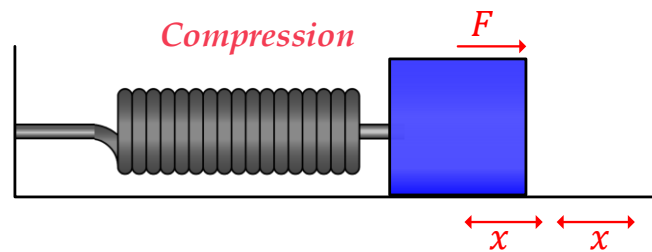




Experiment 04:
**Simple Harmonic
Motion in a Spring-Mass System**



Experiment progression:

This report is prepared by:

	Full name	Remarks	Group
01			
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Simple Harmonic Motion in a Spring-Mass System

1. Objectives

- Students will be able to **explain** the concepts of **simple harmonic motion (SHM)** in the context of a spring-mass system.
- Students will be able to **apply** their understanding of SHM and mechanical energy to **design** and conduct an experiment verifying the principle of energy conservation in the system.

2. Prior Knowledge

What a student should know before the PW

- **Basic mechanics:** Concepts of force, motion (displacement, velocity, acceleration), Newton's Laws of Motion.
- **Work and Energy:** Understanding of work done by a force and different forms of energy (kinetic and potential).

3. Prior Knowledge Test

When an object accelerates due to a force, the object's acceleration is:

- Directly proportional to the force and inversely proportional to the mass.
- Directly proportional to both the force and the mass.
- Inversely proportional to the force and directly proportional to the mass.
- Independent of both force and mass.

- 4. **Definition:** A **spring-mass system** consists of a block attached to a free end of the spring. When it is displaced by x , the spring expands and then comes back

to its original position. In the absence of any resistance and friction, this spring oscillates infinitely. These motions are simple harmonic.

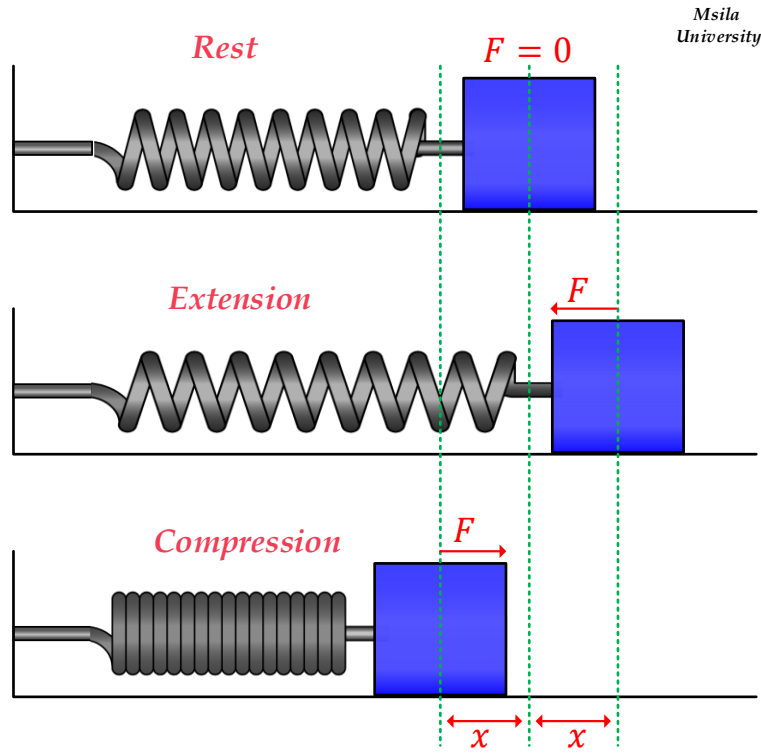


Fig. 1 A horizontal spring-mass system oscillating about the origin

5. System Description

We can describe the motion of the mass using energy principle, since the **mechanical energy of the mass is conserved**. At any position $x(t)$, the mechanical energy E_m of the mass will have a term from the potential energy E_{ep} associated with the spring force, and kinetic energy E_c :

$$E_m = E_c + E_{ep}$$

Fig. 2 represents a graph of energy vs. displacement for a simple harmonic oscillator (a spring-mass system).

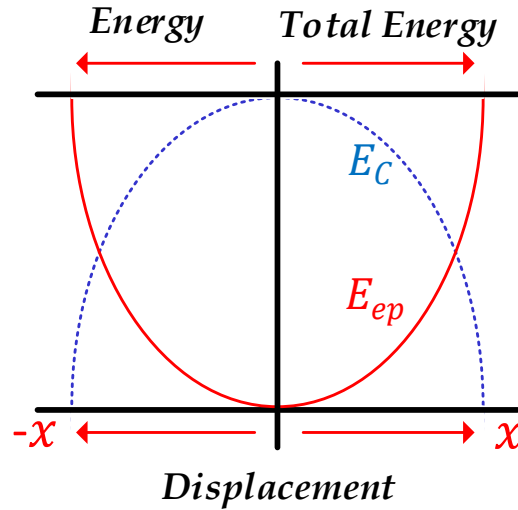


Fig. 2 Energy vs. displacement for a simple harmonic oscillator.

6. System Motion Equation

The motion of the system can be described with differential equation

$$\frac{d^2x}{dt^2} = -\frac{k}{m}x$$

where: $\omega_n = \sqrt{\frac{k}{m}}$ is the natural angular frequency of the system.

The general solution to this equation can be written in form of sinusoidal function

$$x(t) = X_m \cos(\omega_n t + \varphi)$$

7. Energy and simple harmonic oscillator

The kinetic energy of the block can be written as: $E_c = \frac{1}{2}mv^2 = \frac{mX_m^2\omega_n^2}{2}\sin^2(\omega_n t + \varphi)$

we have $\omega_n = \sqrt{\frac{k}{m}}$

So,

$$E_c = \frac{mX_m^2 k}{2m} \sin^2(\omega_n t + \varphi)$$

Thus

$$E_c = \frac{kX_m^2}{2} \sin^2(\omega_n t + \varphi)$$

Potential energy

$$E_{ep} = \frac{1}{2} kx^2 = \frac{kX_m^2}{2} \cos^2(\omega_n t + \varphi)$$

The mechanical energy is the sum of the kinetic and potential energies

$$\begin{aligned} E_m &= E_c + E_{ep} = \frac{1}{2} m v^2 + \frac{1}{2} k x^2 \\ E_m &= \frac{kX_m^2}{2} \sin^2(\omega_n t + \varphi) + \frac{kX_m^2}{2} \cos^2(\omega_n t + \varphi) \\ E_m &= \frac{kX_m^2}{2} \underbrace{[\sin^2(\omega_n t + \varphi) + \cos^2(\omega_n t + \varphi)]}_{=1} \\ E_m &= \frac{kX_m^2}{2} \end{aligned}$$

As a conclusion, we can say that the mechanical energy of the system is constant and conserved

8. Demanded Work

1. Which of the following quantities remains constant in a simple harmonic motion of a mass-spring system?

- Acceleration
- Velocity
- Mechanical Energy (Total Energy)
- Displacement

2. Give the differential equation of the spring-mass system, then demonstrate that the $x(t) = X_m \sin(\omega_n t + \varphi)$ is the solution to the differential equation

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3. What is the velocity of the block when it first comes back to the equilibrium position?

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4. Demonstrate, using the differential equation, that mechanical energy is conserved

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5. Complete the table using the desktop graph simulator

Table: Energy Conservation Verification

	Masse m	Spring constant k	Period T	E_p	E_c	E_{ep}
Case 1	500 g	0.5 N/m
Case 2	750 g	1 N/m
Case 3	1 kg	1.2 N/m
Case 4	1.2 kg	1.5 N/m